

Graph Theory (圖型理論)

阮夙姿

科三422. #4875

Tel:0928523527

五BCD/科三108



Introduction

• 圖論為一在二十世紀快速成長的一門學問。自原本只是組 合數學書中一個章節的短短數頁,百倍增長為如今此一可 單獨研討的學門。它之所以會如此快訴成長,主要的原因 是圖論的應用性非常之廣。諸如:物理、化學、生物、心 理學、社會學等等。而另一個原因則是,在電腦科學理論 上,一些關於處理複雜度的問題,能被轉換成圖論問題來 解決。

Introduction

- 師生晤談時間: 二EF
- 主要教科書: Junming Xu, Theory and Application of Graphs,
 Kluwer Academic Publishers (科大文化代理), 2003.
- 重要參考書籍:
 - 1. West, Introduction to Graph Theory 2ed, Prentice-Hill (全華代理), 2001.
 - 2. Bondy and Murty, Graph Theory with Application. 1976.
 - 3. Balakrishnan and Ranganatha, A Textbook of Graph Theory 2ed, Springer, 2012.
 - 4. 張鎮華,演算法觀點的圖論,台灣大學出版社,2017.



- 課程內容:預計將介紹下列各項
 - 1. Basic Concepts of Graphs
 - 2. Trees and Graphic Spaces
 - 3. Plans Graphs and Planar Graphs
 - 4. Flows and Connectivity
 - 5. Matchings and Independent Sets
 - 6. Coloring Theory

Introduction

 評量方式:最高分99
 作業40% + 平時成績20% + 期中考20% + 期末報告30% + 加分作業

大學部及格60,研究生及格70

• 進度:

第七週、第十週參加會議,補課。

11/29 期中考: Chap 1 ~ Chap 2.

1/3, 1/10: 期末報告

助教: 王怡君:計算理論研究室R307-1(分機4862)
 Office Hour:無,但可以隨時傳訊息問問題。

• 網頁: http://www.csie.ncnu.edu.tw/~jsjuan/courses.html





暨大資工系 教育目標



- 1. 配合國家經濟發展,培養符合資訊產業需求的工程技術人才
- 2. 配合國家科技及學術發展,培養具備前瞻資訊科技研發能力的人才
- 3. 配合全球永續發展潮流,培養具備國際視點或tieLS程倫理Lan人文關懷及社會責任的科技人才



暨大資工系 核心能力

基礎數理

理論

研究所核心能力設計

1. 具備資訊科學基礎數理知識並應用於發掘、分析與解釋數據的能力

2. 具備程式設定基礎知識並應用於設計及實作資訊軟體的能力

3. 具備使用英文閱讀資訊領域技術文件及學術論文的能力

4. 具備團隊合作及獨立執行資訊工程領域學術研究的能力

5. 具備撰寫學術論文的能力

6. 理解資訊工程專業倫理、敬業態度、環境保護及社會責任

英文能力

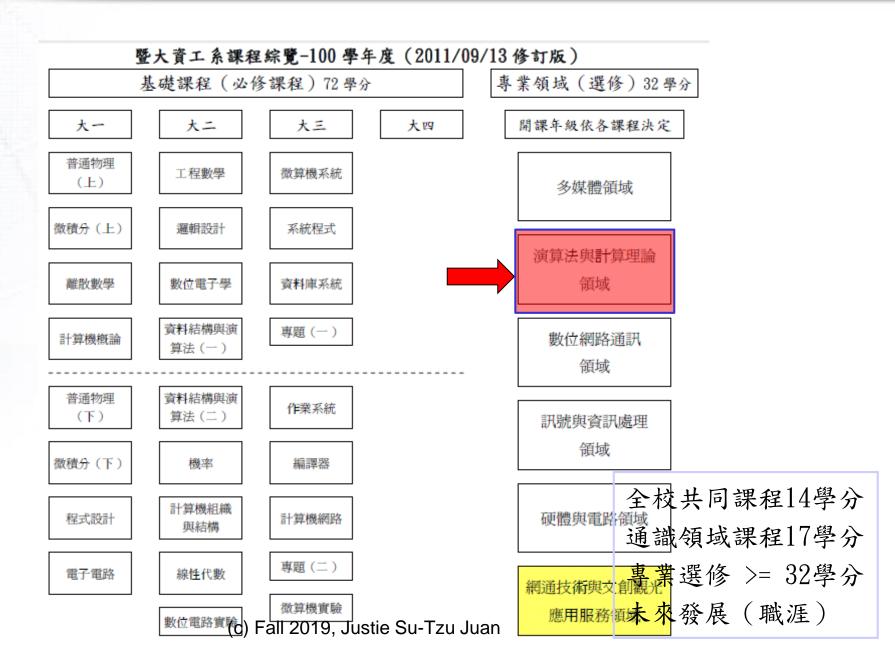
合作與獨立

生命品格

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暨大資工系 課程地圖(部分)

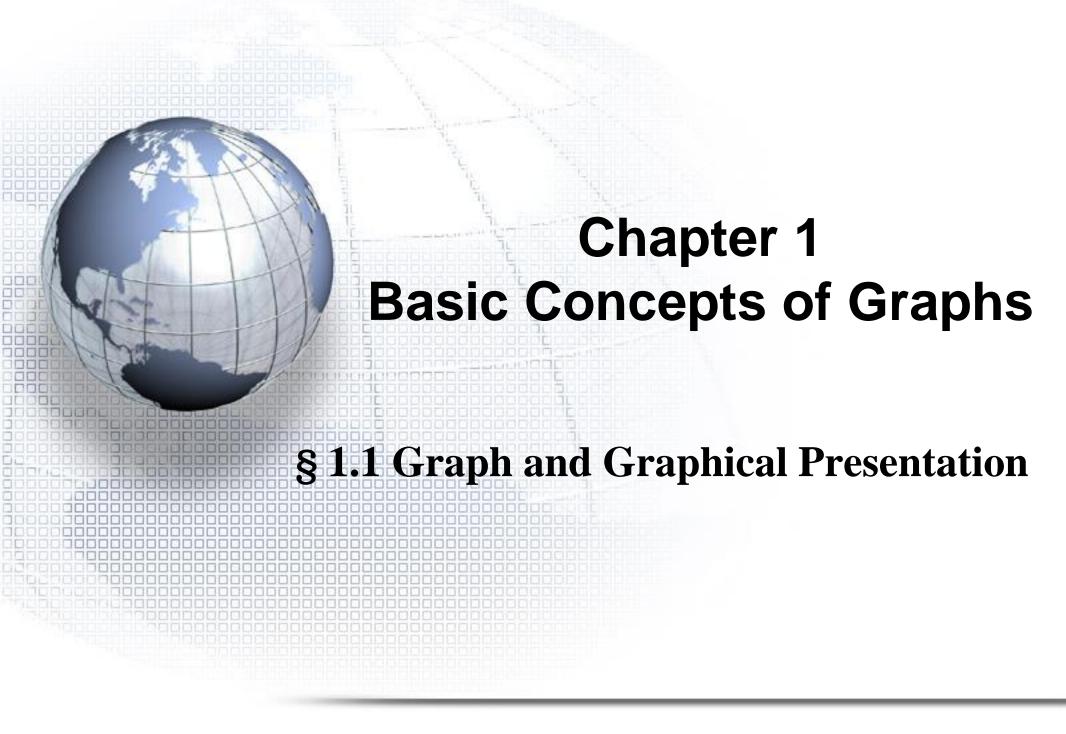




- → 1. 專業知識與實務技能
- → 2. 創新與獨立思考能力
 - 3. 溝通表達與團隊合作精神
- → 4. 專業倫理與社會責任認知
 - 5. 掌握國際趨勢與全球視野



- → (一)道德思辨與實踐能力
 - (二)人際溝通與表達能力
- ⇒ (三)獨立思考與創新能力
- → (四)人文關懷與藝術涵養
- → (五)專業知能與數位能力
 - (六)團隊合作與樂業倫理
 - (七)全球視野與尊重多元文化
 - (八)社區參與與公民責任





• Def:

- A graph G is an ordered triple (V, E, ψ) , where V, E: disjoint sets; $\psi: E \to V \times V$: a mapping.
- V: vertex-set; $x \in V$: vertex E: edge-set; $e \in E$: edge ψ : incidence function; if $\psi(e) = (x, y)$: x, y are end-vertices of e.

• Example 1.1.1:

```
D = (V(D), E(D), \psi_D) \text{ is a digraph, where}
V(D) = \{x_1, x_2, x_3, x_4, x_5\},
E(D) = \{a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8, a_9\}
and \psi_D is defined by \psi_D(a_1) = (x_1, x_2), \psi_D(a_2) = (x_3, x_2), \psi_D(a_3) = (x_3, x_3),
\psi_D(a_4) = (x_4, x_3), \psi_D(a_5) = (x_4, x_2), \psi_D(a_6) = (x_4, x_2),
\psi_D(a_7) = (x_5, x_2), \psi_D(a_8) = (x_2, x_5), \psi_D(a_9) = (x_3, x_5).
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• Example 1.1.2:

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H = (V(H), E(H), \psi_H) is a digraph, where V(H) = \{y_1, y_2, y_3, y_4, y_5\},\ E(H) = \{b_1, b_2, b_3, b_4, b_5, b_6, b_7, b_8, b_9\} and \psi_H is defined by \psi_H(b_1) = (y_1, y_2), \psi_H(b_2) = (y_3, y_2), \psi_H(b_3) = (y_3, y_3),\ \psi_H(b_4) = (y_4, y_3), \psi_H(b_5) = (y_4, y_2), \psi_H(b_6) = (y_4, y_2),\ \psi_H(b_7) = (y_5, y_2), \psi_H(b_8) = (y_2, y_5), \psi_H(b_9) = (y_3, y_5).
```

• Def:

- If $V \times V$ is a set of ordered pair (x, y)'s, then
 - ① G is called directed graph (digraph).
 - $@ e \in E;$ directed edge (arc).
 - ③ if $\psi(e) = (x, y)$: x is called the tail of e; y is called the head of e; e is called an out-going edge of x; in-coming edge of y.



Def:

- If $V \times V$ is a set of unordered pair $\{x, y\}$'s, then
 - ① G is called an undirected graph.
 - ② Use xy or yx instead of $\{x, y\}$.
 - ③ e ∈ E: undirected edges.

• Example 1.1.3:

 $G = (V(G), E(G), \psi_G)$ is an undirected graph, where $V(G) = \{z_1, z_2, z_3, z_4, z_5, z_6\},$ $E(G) = \{e_1, e_2, e_3, e_4, e_5, e_6, e_7, e_8, e_9\}$ and ψ_G is defined by $\psi_G(e_1) = z_1 z_2, \ \psi_G(e_2) = z_1 z_4, \ \psi_G(e_3) = z_1 z_6,$ $\psi_G(e_4) = z_2 z_3, \ \psi_G(e_5) = z_3 z_4, \ \psi_G(e_6) = z_3 z_6,$ $\psi_G(e_7) = z_2 z_5, \ \psi_G(e_8) = z_4 z_5, \ \psi_G(e_9) = z_5 z_6.$



Def:

- loop: ex: $\psi(e) = (x, x)$.
- parallel edges (multi-edges): ex: $\psi(e_1) = (x, y) = \psi(e_2)$
- $-E_G(x, y) = \{e \in E(G): \psi(e) = (x, y)\}$
- $\mu_G(x, y) = |E_G(x, y)|$
- $-\mu(G) = \max\{\mu_G(x,y): \forall x,y \in V(G)\}: \text{ the multiplicity of } G.$

• ex: in Example 1.1.1:

```
D = (V(D), E(D), \psi_D) \text{ is a digraph, where}
V(D) = \{x_1, x_2, x_3, x_4, x_5\},
E(D) = \{a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8, a_9\}
and \psi_D is defined by \psi_D(a_1) = (x_1, x_2), \psi_D(a_2) = (x_3, x_2), \psi_D(a_3) = (x_3, x_3),
\psi_D(a_4) = (x_4, x_3), \psi_D(a_5) = (x_4, x_2), \psi_D(a_6) = (x_4, x_2),
\psi_D(a_7) = (x_5, x_2), \psi_D(a_8) = (x_2, x_5), \psi_D(a_9) = (x_3, x_5).
```

 a_5 , a_6 are parallel edges,

 a_7 , a_8 are not.

 a_3 is a loop.

- Def: graphical presentation
- ex: in Example 1.1.1:

$$D = (V(D), E(D), \psi_D)$$
 is a digraph, where

$$V(D) = \{x_1, x_2, x_3, x_4, x_5\},\$$

$$E(D) = \{a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8, a_9\}$$

and
$$\psi_D$$
 is defined by $\psi_D(a_1) = (x_1, x_2), \ \psi_D(a_2) = (x_3, x_2), \ \psi_D(a_3) = (x_3, x_3),$

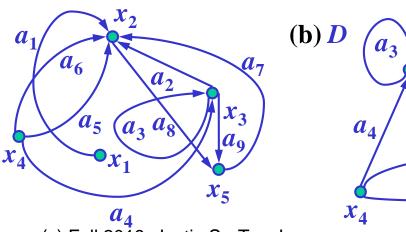
$$\psi_D(a_4) = (x_4, x_3), \ \psi_D(a_5) = (x_4, x_2), \ \psi_D(a_6) = (x_4, x_2),$$

$$\psi_D(a_7) = (x_5, x_2), \ \psi_D(a_8) = (x_2, x_5), \ \psi_D(a_9) = (x_3, x_5).$$

 a_{5}

• Figure 1.1,

(a) **D**



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• ex: in Example 1.1.3:

 $G = (V(G), E(G), \psi_G)$ is an undirected graph, where

$$V(G) = \{z_1, z_2, z_3, z_4, z_5, z_6\},\$$

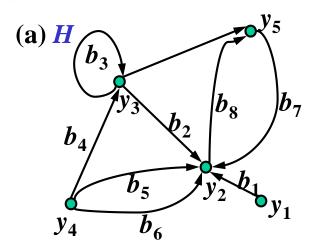
$$E(G) = \{e_1, e_2, e_3, e_4, e_5, e_6, e_7, e_8, e_9\}$$

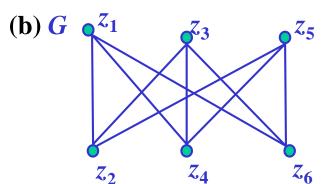
and
$$\psi_G$$
 is defined by $\psi_G(e_1) = z_1 z_2$, $\psi_G(e_2) = z_1 z_4$, $\psi_G(e_3) = z_1 z_6$,

$$\psi_G(e_4) = z_2 z_3, \ \psi_G(e_5) = z_3 z_4, \ \psi_G(e_6) = z_3 z_6,$$

$$\psi_G(e_7) = z_2 z_5, \ \psi_G(e_8) = z_4 z_5, \ \psi_G(e_9) = z_5 z_6.$$

• Figure 1.2

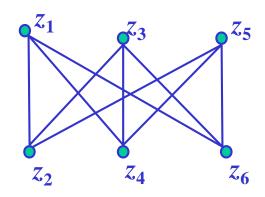






• Def:

- incident: vertex \leftrightarrow edge.
- adjacent: vertex \leftrightarrow vertex; edge \leftrightarrow edge.
- loopless
- simple: a graph contains neither loops nor parallel edges.
 - ψ is injective (1-1)
 - use $V \times V$ instead of E. i.e. write (V, E) for (V, E, ψ)
- ex: In Example 1.1.3, write as : G = (V(G), E(G)), where $E(G) = \{z_1z_2, z_1z_4, z_1z_6, z_2z_3, z_3z_4, z_3z_6, z_2z_5, z_4z_5, z_5z_6\}$.



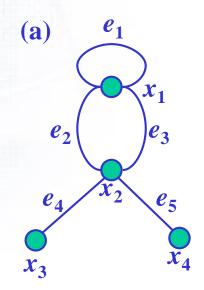


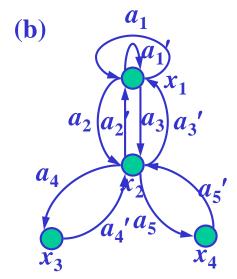
• Def:

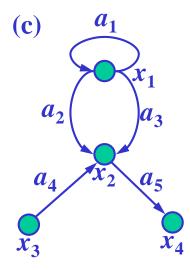
- An undirected graph can be thought of as a symmetric digraph, in which there are two symmetric edges, one in each direction, corresponding to each undirected edge.
 - \rightarrow digraph is more general!!
- G is the underlying graph of $D \equiv D$ is an oriented graph of G.



- ex: Figure 1.3 (a) an undirected graph,
 - (b) (a)'s symmetric digraph,
 - (c) (a)'s an oriented graph.









- Def: Let $G = (V, E, \psi)$ be a graph,
 - v = |V| (= n(G)), is called order of G. (書上印成v)
 - $\varepsilon = |E| (= m(G))$, is called size of G.
 - A graph is empty if $\varepsilon = 0$.
 - A empty graph is trivial if $\nu = 1$.
 - non-trivial \equiv not trivial.
 - A graph is finite if both ν, ε are finite. (本書只討論 finite graph)
 - $-\lceil r\rceil, \lfloor r\rfloor, \binom{n}{k}$



• Example 1.1.4: In any group of six people, there must be three people who get to either know each other or not.

Proof.

Let points A, B, C, D, E, F on the plane to denote these 6 people.

Draw red line joining two points if they have known each other, blue line joining two points if not.

Now, consider F, there exist three lines of the same color which are incident with F.

(Without loss of generality) W.L.O.G.,

suppose they are three red lines FA, FB, FC.

Consider $\triangle ABC$, if it has no red line, then \exists blue $\triangle ABC$, else it has a red line, say AB, then \exists red $\triangle ABF$.

That means, either \exists three people (ABF) know each other, or \exists three people (ABC) don't know each other.



• Exercise: 1.1.1, (剩下的請至少看過題目)